Carnegie Mellon University

Edge Intelligent Sensor for In-Situ AM Inspection and closed-loop control

NextManufacturing



Challenges in Al-enabled Additive Manufacturing (AM)

Lacks *in-situ* process monitoring and inspection [ARL/ NextM]

Only post-inspection \Rightarrow Time lost and cost Bad generalizability 🌣 Relies on Data & Label 🧚Ki

Lacks *in-situ* process control [Boeing]

Multivariate build process \Rightarrow Inconsistency Unobservable parameters \Leftrightarrow Randomness

Applications

Initiative Large Metal Parts (WAAM)

BOEING

Futures



MFI2022 New Project - rWAAM

Edge Sensor for Additive Manufacturing

Technology Highlights

★ Confined space RGB-D inspection ★ Sensor for closed-loop manufacturing ★Infrastructure free visual-inertial SLAM ★Edge processing for machine learning









Aerospace composite Hybrid Mfg



Defect detection

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In-situ Inspection and Machine Learning for AM

In-situ Inspection using Semi-Supervised ML

Reduced reliance on expert-labeled data

Semi-supervised learning uses an unlabeled dataset

- for pre-training (generalizable to new skills)
- Up to 10x smaller labeled database used f
- finetuning to specific defects detection

Methods: Semi-Supervised Defect Detection Framework

Finetuning

ARI

- Train on un-labeled Data A
- Fine-tune on labeled Data B
- Self-similarity described by process parameters
- Image embeddings from pretrained neural network

Results: Comparison across 5 tasks

Result: Embedding Distances

Robotic closed-loop planning and control for AM

Sensor-based Closed-loop AM Processes

Incorporating in-process local replanning

Adapting the tool path to accommodate for defects in AM part

Sensor-based Coverage Planning

Optimal path planning for 3D scanning and printing processes using sensory information

Methods: Scan-Plan-Print-Repair Paradigm

